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TM12 TM14

High payload with extended reach

SMART

Built-in vision system, Masters in robot vision

SIMPLE

Revolutionary user interface, Easy to deploy

SAFE

Complies with ISO10218-1 & ISO/TS 15066



TM12/TM14

Class leading payload and reach

The TM12 & TM14 offer class leading payload and reach capabilities. The TM12 offers 12Kg payload and a 1300mm reach and the TM14 offers a 14Kg payload and 1100mm reach.

Like the TM5 the new increased specification robots are easy to deploy, are highly flexible, are maintenance free and provide a high performance automation solution for manufacturing.

Built in vision system

The TM range of collaborative robots comes with an integrated hardware and software vision package. Functions such as shape matching, barcode & QR code reading, colour recognition, OCR etc are all easily configured from the integral robot design toolbox.

Applications

Logistics - handling - de-burring - polishing - semiconductor transportation - palletising

TM12M/TM14M Mobile robot product series

The TM-M Series offers solutions for AGV and mobile vehicle integration

The TM-M series are powered by a DC 20-60V supply, making them compatible with most brands of AGV's and mobile vehicles. By utilising the "TM-Landmark", the mobile robot can orientate itself within a 3D space, like an auto datum sequence, to multiple machine surfaces. This allows the TM-M robots to operate between two or more locations seamlessly.

Specification









| Model | | TM12 | TM14 | TM12M | TM14M | |
|-------------------------------------|---------------------|---|-----------------------------|--------------------------|----------|--|
| Weight | | 33.3Kg | 32.6Kg | 33.3Kg | 32.6Kg | |
| Payload | | 12kg | 14kg | 12kg | 14kg | |
| Reach | | 1300mm | 1100mm | 1300mm | 1100mm | |
| Max Speed | | 1.3m/s | 1.1m/s | 1.3m/s | 1.1m/s | |
| Joint ranges | J1 | +/- 270° | | | | |
| | J2,J4,J5 | +/- 180° | | | | |
| | J3 | +/- 166° | +/- 163° | +/- 166° | +/- 163° | |
| | J6 | +/- 270° | | | | |
| Speed | J1~J2 | 120°/s | | | | |
| | J3 | 180°/s | | | | |
| | J4~J5 | 180°/s | 150°/s | 180°/s | 150°/s | |
| | J6 | 180°/s | | | | |
| Repeatability | | +/- 0.1 mm | | | | |
| Degrees of freedom | | 6 rotating joints | | | | |
| I/O ports | | Control box | | Tool conn. | | |
| | Digital in | 16 | | 4 | | |
| | Digital out | 16 | | | 4 | |
| | Analog in | 2 | | 1 | | |
| | Analog out | 1 | | 0 | | |
| I/O power supply | | 24V 1.5A for control box and 24V 1.5A for tool | | | | |
| IP classification | | IP54 | | | | |
| Power Consumption | | Typical 300 watts Typical 300 watts | | | | |
| Maximum Power Capacity ^① | | Max. 2200 watts Max. 1500 Watts ® | | | | |
| Temperature | | The robot can work in a temperature range of 0-50°C | | | | |
| Power supply | | 100-240 VAC, 50-60 Hz DC 20V~60V | | | | |
| I/O Interface | | 3×COM, 1×HDMI, 3×LAN, 4×USB2.0, 2×USB3.0 | | | | |
| Certification | | CE, SEMI S2(Option) | | | | |
| Variation Models | | X: without hand eye camera, SEMI: SEMI S2 certified | | | | |
| Robot Vision | | | | | | |
| Eye in Hand (Built in) | | 1.2M/5M pixels, color camera | | | | |
| Eye to Hand (Optional) | | Support Maximum 2 GigE cameras | | | | |
| Maximum por | wer capacity is the | maximum output capacity of t | he power supply system desi | gned in the control box. | | |

Maximum power capacity can be expanded to 2500 Watts with an external 1000 watts power supply